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Accident avoidance by active intervention for Intelligent Vehicles

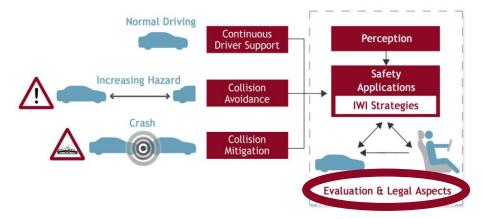


Martijn van Noort, TNO interactIVe Final Event

20th-21st November 2013

### Content

- Approach
- Accident re-simulation
- Rear-end case
- Run-off road case
- Scaling up of Results on EU level





# Safety impact assessment

 What would be the effect of interactIVe functions on the number of fatalities and injuries if they were deployed in Europe?

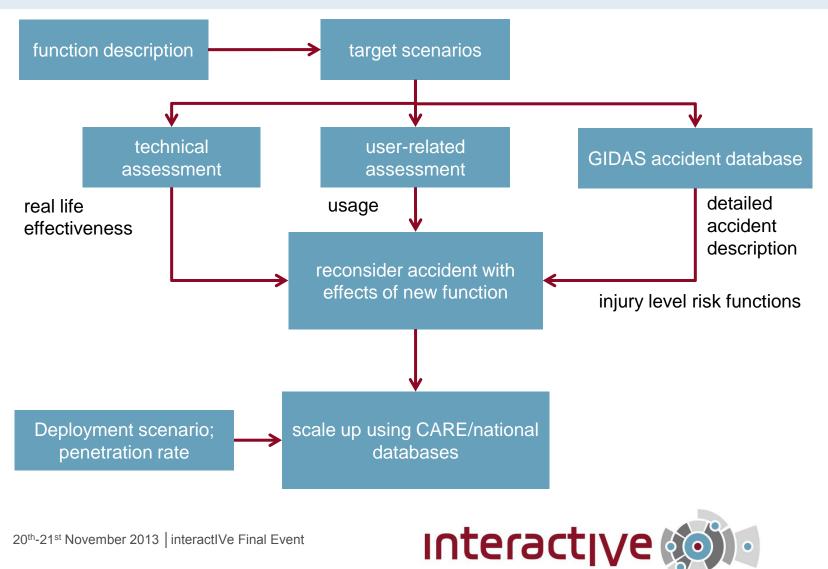


Characteristics

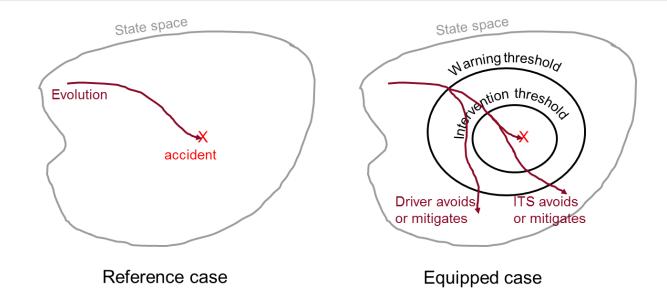
- Prototype systems → Limited amount of test results available on technical performance and user behaviour → ex ante evaluation
- Many different functions, combinations of functions, and demonstrators
  → evaluation of the functions
- Need in-depth accident data to define accident scenarios, but not available on EU level
- Most of the functions address
  - Rear end
  - Road departure
  - Lane change



## Approach



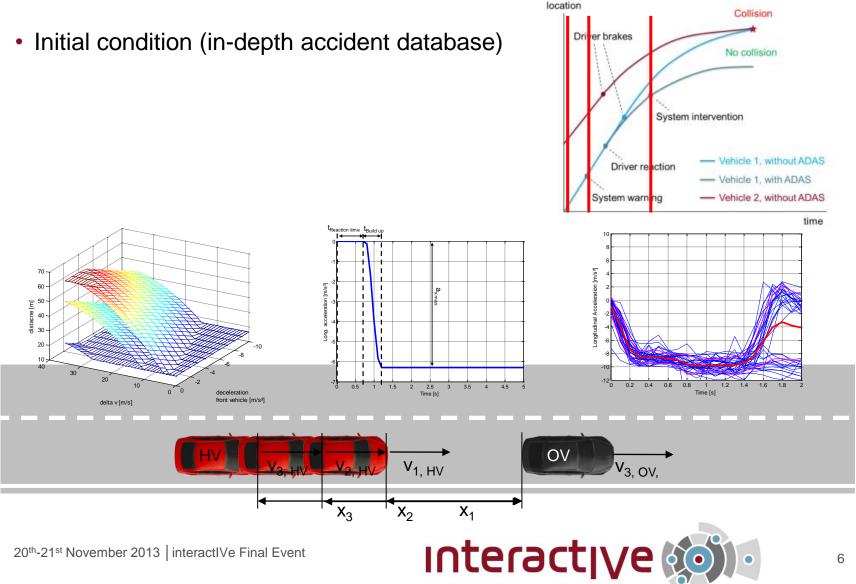
# Accident re-simulation



- Function may warn or intervene. Examples:
  - Continuous Support (CS): only warning
  - Collision Mitigation System (CMS): only intervening
  - Rear-End Collision Avoidance (RECA): both
- Driver may react to warning



### Rear-end scenario (Braking)



#### Accident re-simulation for rear end

- Example rear end accident scenario •
- With Rear-End Collision Avoidance (RECA) function



# Re-simulation results for rear end

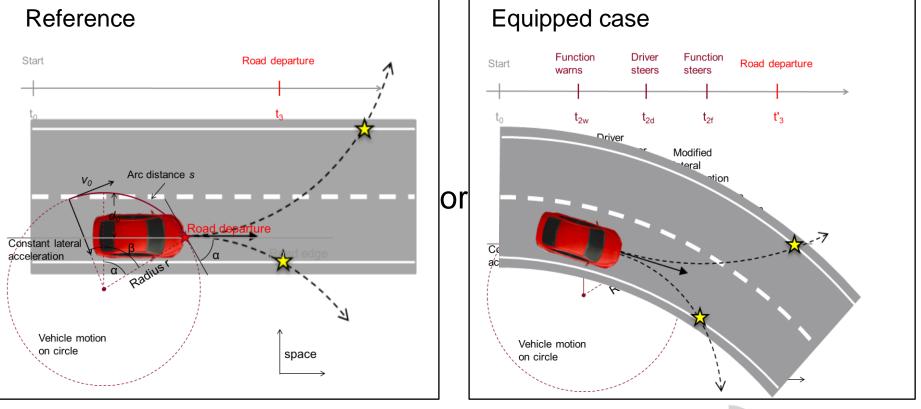
<b>RECA</b> truck	Driver+System intervention			71%					30%	
RECA car	Driver+System intervention 1	%	22%				77%			
ESA car	System intervention only		21%	2%			77%			
car	Driver reaction only	8%			65	5%			27%	
CS	Driver reaction only 1	% 8%				70%	1		21%	
CMS car	System intervention only		24%		42%			34%		
	0%			)%	40	% 60	)%	80	9%	100%
	outside speed operationa	l condi	tions	no effect col		collision mitig	collision mitigated		collision avoided	

- 364 in-depth accident cases analysed
- Relevant for 4 functions
- Varying results: 21% 77% rear ends potentially avoided, others mitigated
- This holds for selection of GIDAS scenarios



# Road departure

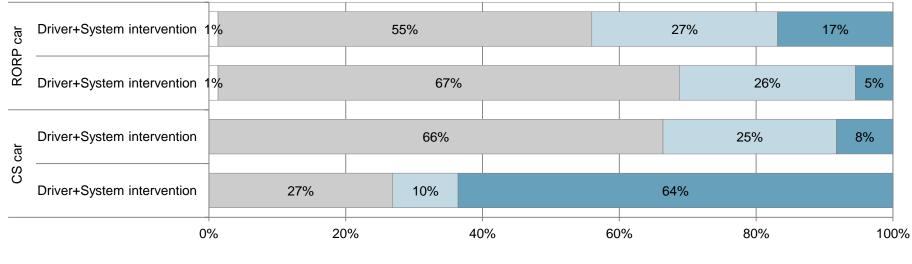
- Only avoidance
- Only steering
- Similar for curved roads



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# Re-simulation results for road departure

#### Road departure (all roads)



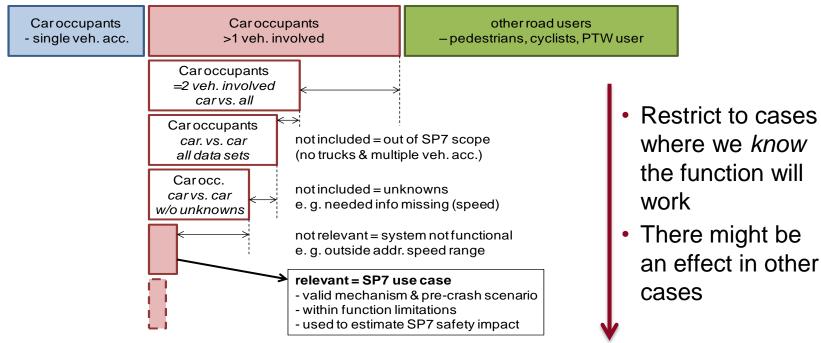
□ outside speed operation conditions □ road departure > 0.5 m □ road departure <= 0.5 m ■ road departure avoided

- 150 in-depth accident cases analysed, relevant for 2 functions
- Departure (over lane marking): 5 64% potentially avoided
- Departure 50 cm outside lane marking: 31 74%
- Trade-off between effectiveness and acceptance



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# Scaling up on the EU level





Relevant EU accident population (% on all EU casualties)severely inj.fatally inj.Road departure case3.14%5.14%

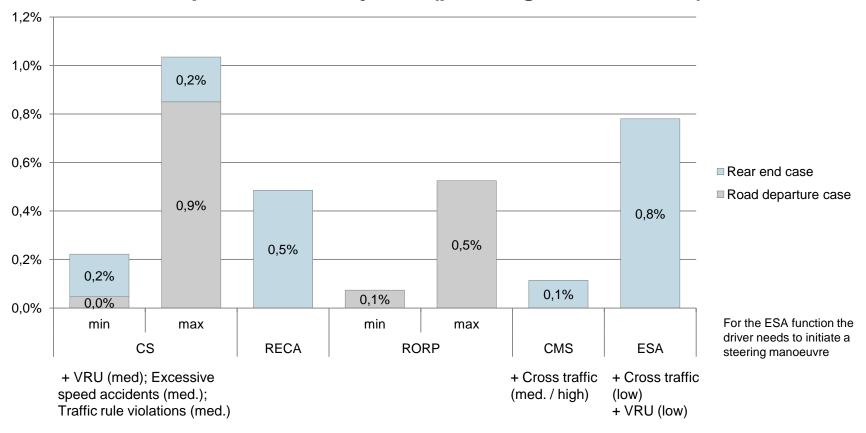
2.33%



0.78%

Rear end case

### EU level results for rear end and road departure



#### Impact on fatal injuries (passenger cars, EU-27)



#### Conclusions

- interactIVe safety functions have significant potential to improve safety by avoiding or mitigating accidents
- Results are widely varying between functions. For the GIDAS data:
  - 21%-77% rear ends potentially avoided, many others mitigated
  - 5%-74% road departures potentially avoided
- At EU level: ~1% of all fatalities saved in some rear end & road departure cases (5% of all cases)
  - Additional savings for other accident types and scenarios
- Accident reconstruction method is suitable for ex ante study. Limitations:
  - Re-simulation is first approximation, adapted to available data.
  - Modelling of realistic driver reactions needs more data.
  - GIDAS accident scenarios are for a specific region
  - Nr of fatal accidents in GIDAS is low, especially for rear end
- Thus, method provides safety *potential* rather than "real" safety impact.
- Acknowledgement: interactIVe "Evaluation and Legal Aspects" team



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#### Thank you.

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TNO





SEVENTH FRAMEWORK PROGRAMME